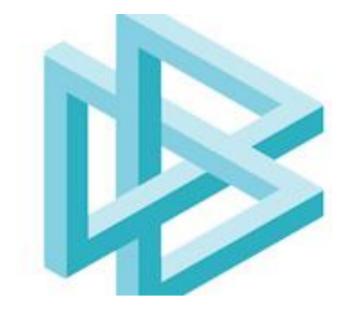


XVII Congreso de Confiabilidad

25 y 26 de noviembre de 2015. Parque Científico y Tecnológico de Bizkaia. Zamudio (Bizkaia)







APPLICATION OF HEALTH AND USAGE MONITORING SYSTEM (HUMS) TO IMPROVE THE FLIGHT SAFETY IN A FLIGHT CONTROL ELECTRO-MECHANICAL ACTUATOR (EMA)

Ricardo de Arriba

RAMS & ILS Engineer

Alberto Gallego

Product Support Manager

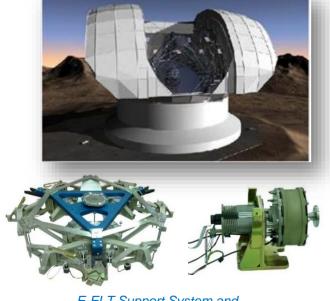
COMPAÑÍA ESPAÑOLA DE SISTEMAS AERONÁUTICOS (CESA)



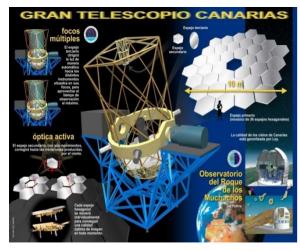


XVII Congreso de Confiabilidad

• CESA - Compañía Española de Sistemas Aeronáuticos

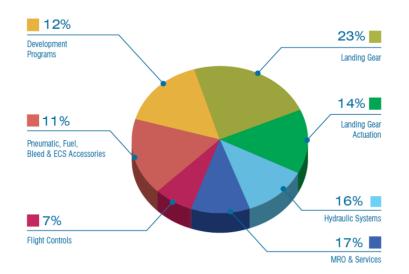


E-ELT Support System and Position Actuator





CESA Shareholders







A330 tail boom HOIST and ERAS





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CESA PRODUCTS



Cargo Door Actuator

Ramp Actuator





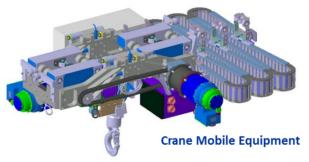


Ejector Parachute Extraction System



Tow Plate





A380 Reservoir

Hydraulic Reservoirs A400m (Purchaser : Airbus Germany)





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XVII Congreso de Confiabilidad

<u>CESA participation in European Projects</u>





REliability and Safety Enhanced electrical Actuation System ARCHitectures.



FLIGHT EMA

(e-RUDDER)

Advanced Flight Control System – Design Development and Manufacturing of an Electro Mechanical Actuator with associated Electronic Control Unit and Dedicated test Bench





Design, development and manufacturing of an electro-mechanical actuator and test rig for AiRcrafts Main LandIng Gear acTuation systems





Modular Electro Mechanical Actuators for ACARE 2020 aircraft and helicopters

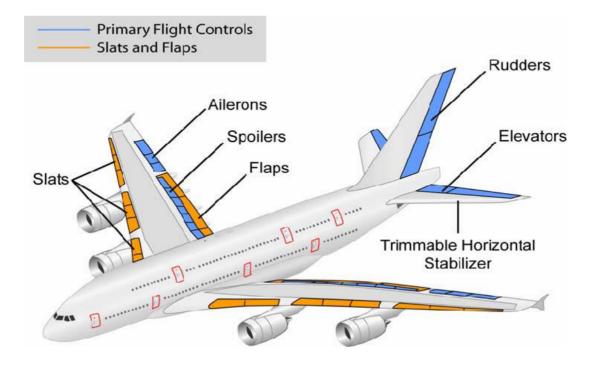
Others: GreenAir, SuperSkySense, Fastwing, IND-Dampers, Titalum, Newtiral, POA, LAMA, ELGAR, NIPSE...







- More Electrical Aircraft (MEA): objectives for the next generation of aircrafts and helicopters => to improve the fuel consumption, the efficiency of their systems and reduce their environmental impact.
- Objective : to implement electrical actuation of control surfaces, using Electro Mechanical Actuators (EMA).

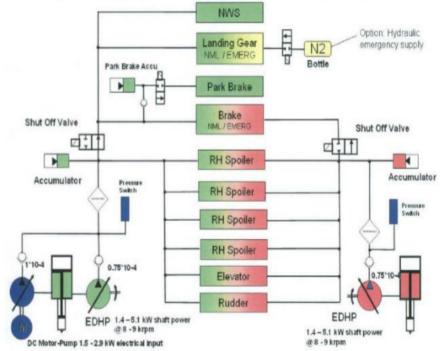






 To substitute hydraulic circuits, including pumps, reservoirs, accumulators and so on, using Electro Mechanical Actuators (EMA).

- Operation and safety issues:
 - > thermal behavior,
 - > power electronics optimization
 - life duration
 - mechanical jamming susceptibility









AIRWORTHINESS REQUIREMENTS (CS-25.1309)

- Definition of CAT/HAZ/MAJ requirements
- No single failure will result in a Catastrophic Failure Condition;
- Each Catastrophic Failure Condition is Extremely Improbable

| Effect on | No effect on | Slight reduction | Significant | Large reduction | Normally with |
|----------------------------|---------------------------------------|--|--|----------------------------|-------------------|
| Aeroplane | operational | in functional | reduction in | in functional | hull loss |
| | capabilities or | capabilities or | functional | capabilities or | |
| | safety | safety margins | capabilities or | safety margins | |
| | | | safety margins | | |
| Effect on | Inconvenience | Physical | Physical | Serious or fatal | Multiple |
| Occupants | | discomfort | distress, | injury to a small | fatalities |
| excluding Flight Crew | | | possibly including | number of passengers or | |
| CIEW | | | injuries | cabin crew | |
| | | | injunos | CODITICION | |
| Effect on Flight | No effect on | Slight increase | Physical | Physical | Fatalities or |
| Crew | flight crew | in workload | discomfort or a | distress or | incapacitation |
| | | | significant | excessive | |
| | | | increase in | workload | |
| | | | workload | impairs ability to | |
| | | | | perform tasks | |
| Allowable | No Probability | <probable< td=""><td><remote< td=""><td>Extremely</td><td>Extremely</td></remote<></td></probable<> | <remote< td=""><td>Extremely</td><td>Extremely</td></remote<> | Extremely | Extremely |
| Qualitative | Requirement | > | > | <> | Improbable |
| Probability | | | | Remote | |
| Allowable | No Probability | <> | <> | <> | |
| Quantitative | Requirement | | - | - | |
| Probability: | | <10 ⁻³ | <10 ⁻⁵ | <10 ⁻⁷ | <10 ⁻⁹ |
| Average Probability per | | Note 1 | | | |
| Flight Hour on | | Note | | | |
| the Order of | | | | | |
| | | | | | |
| Classification of | No Safety Effect | <minor< td=""><td><major< td=""><td><hazardous></hazardous></td><td>Catastrophic</td></major<></td></minor<> | <major< td=""><td><hazardous></hazardous></td><td>Catastrophic</td></major<> | <hazardous></hazardous> | Catastrophic |
| Failure | | > | > | | |
| Conditions | | | | | |
| | | | | applicant is not req | |
| | | | | erical criteria has b | |
| Failure Conditions | Current transport | category aeroplan | e products are rega | rded as meeting th | is standard simp |

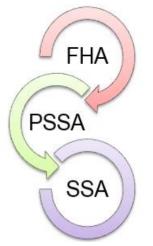
by using current commonly-accepted industry practice







- SYSTEM SAFETY ASSESSMENT PROCESS
 - Process according to ARP-4761
 - FHA: identify functional hazards



PSSA: architecture of system according to safety

objectives

SSA: evaluation of system to show safety objectives







SYSTEM SAFETY ASSESSMENT PROCESS => FHA

| 1 Function | 2 Failure Condition (Hazard Description) | 3 Phase | 4 Effect of Failure Condition on Aircraft/Crew | 5 Classification | 6 Reference to Supporting Material | 7 Verif. |
|--|---|---------------------------------------|--|------------------|--|----------|
| Longitudinal stability (Pitch) Control of the Aircraft | | Take-off / Approach and Landing | See below | | | |
| | a. Loss of both Elevators control | Approach and Landing | No command response of the surfaces. Even detected, it can lead to loss of aircraft longitudinal stability control, and the loss of the aircraft, especially with adverse environmental conditions (cross wind). | CATASTROPHIC | | FTA |
| | | Climb / Cruise / Descent | | HAZARDOUS | | FTA |
| | b. Jamming of both Elevators | Approach and Landing | Both surfaces stuck. Even detected, it can lead to loss of aircraft longitudinal stability control, and the loss of the aircraft, especially with adverse environmental conditions (cross wind). | CATASTROPHIC | | FTA |
| | | Climb / Cruise / Descent | | HAZARDOUS | | FTA |
| | Partial loss of pitch control | Take-off / Approach and Landing | See below | | | |
| | | Approach and Landing | Increase of crew workload and reduction of pitch control capabilities Excessive loads could be applied on rear fuselage, there may be some near ground flight conditions where the minimum required gradient may not be achieved and there could be a stall risk loss of aircraft longitudinal stability control, and the loss of the aircraft, especially with adverse environmental conditions (cross wind). | CATASTROPHIC | Additional study necessary to determine the severity. Conservative approach is kept. Depending on aircraft dynamics, it is needed to analyse if ailerons could mitigate these effects under extreme conditions | |



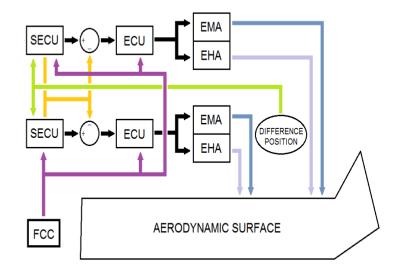




- SYSTEM SAFETY ASSESSMENT PROCESS
 - Result of FHA=> set of System Level Requirements
 - Trade off of the different architectures (based on "no single failure principle"
 - two Elevator surfaces, with two actuators each

(1 EMA + 1 EHA or 2 EMA).

Control is made by two System Electronic
 Controller (SECU) connected and one
 Electronic Controller (ECU) per Actuator



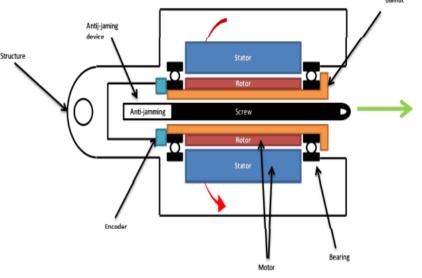






SYSTEM SAFETY ASSESSMENT PROCESS => PSSA

- Fault Tree Analysis
- Common Cause Analysis
- Definition of Development Assurance
- Definition of scheduled maintenance safety-related tasks
- Definition of requirements at equipment level









- SYSTEM SAFETY ASSESSMENT PROCESS => SSA
 - Fault Tree Analysis
 - Common Cause Analysis
 - FMEA/FMES at system item



- Definition of Development Assurance Level for System Items
- Validation of Failure Condition Classifications
- Verification of the Safety requirements identified in the FHA

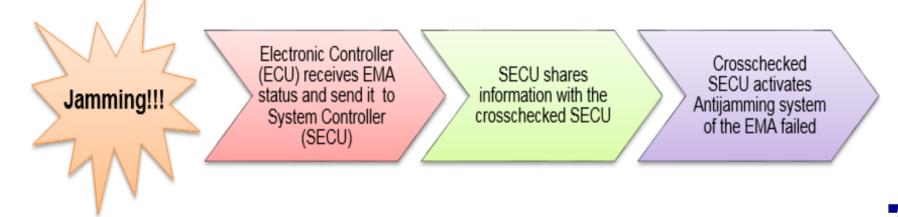






- SAFETY CHALLENGE (From SERVOHYDRAULIC ACTUATOR to EMA)
 - Critical issue: jamming of EMA mechanical items
 - Single failure leading to CAT effect.
 - CESA solution: anti-jamming system => assuring the free

movement of the Flight Surface governed by the redundant







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actuator







HUMS CONCEPT

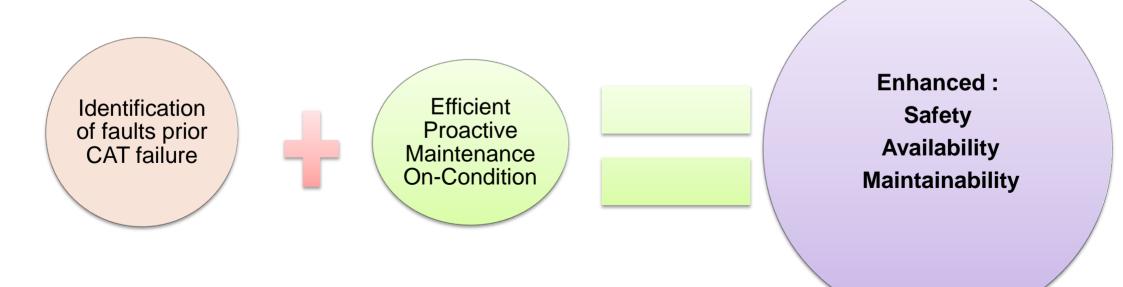
- ➢ <u>HEALTH MONITORING:</u>
 - diagnosis and isolation of faults
 - Monitor internal parts to deliver feedback to SECU/ECU
 - Definition of sensors and variables to measure by means of FMEA
- USAGE (PROGNOSIS)
 - Usage module integrates models able to predict failures in critical items







Benefits of HUMS









Measurement of System Efficiency Life estimation Comparison of health monitoring with "Ideal Development and endurance test data recorded to get an "Ideal Efficiency" curve Curve" implemented in Control System Simulation of degradations: loss of grease, overload in bearings, dust in ballscrew Frequency spectrum Cycle counter with variables record Health Monitoring from Sensors Load. Histogram of performance recorded in each • current, operation • temperature, Normalized cycle to be tested to estimate the Motor rotational position maximum number of remaining cycles of the Actuator lineal position actuators







Measurement of System Efficiency

- Development and endurance test data recorded to get an "Ideal Efficiency" curve implemented in Control System
- Simulation of degradations: loss of grease, overload in bearings, dust in ballscrew
- Frequency spectrum







Health Monitoring from Sensors

- Load,
- current,
- temperature,
- Motor rotational position
- Actuator lineal position







Life estimation

- Comparison of health monitoring with "Ideal Curve"
- To analyse to be able to predict the increase (or reduction) of life of equipment.
- To analyse the possibility to include comparison in real time







Cycle counter with variables record

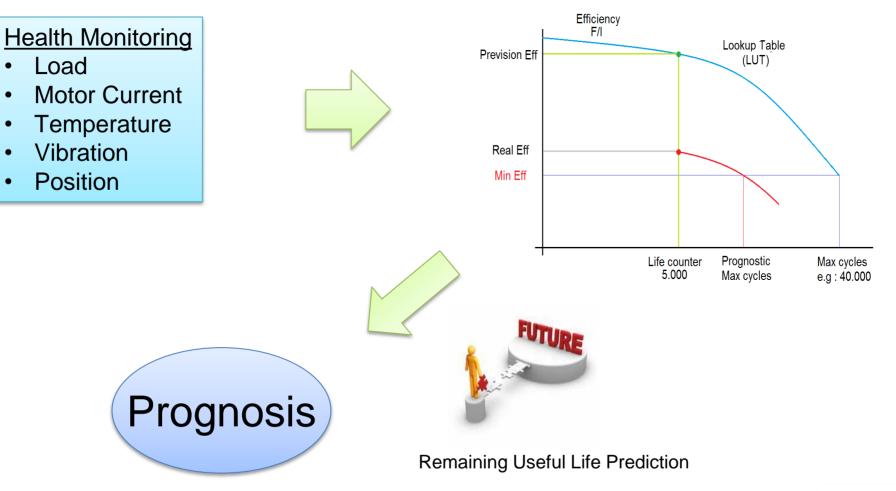
- Histogram of performance recorded in each operation
- Normalized cycle to be tested to estimate the maximum number of remaining cycles of the actuators







HUMS implementation in SECU



Test correlations / mathematical algorithms

